Time	Saturday 14 July (Location: Room B4)	
08:20 to 08:30	Welcome & opening remarks	
08:30 to 09:30	Keynote: Shimon Whiteson. Talk title TBC	
09:30 to 10:00	Long talk: Diederik M. Roijers, Luisa M Zintgraf, Pieter Libin and Ann Nowe. Interactive Multi-Objective Reinforcement Learning in Multi-Armed Bandits for Any Utility Function	
10:00 to 10:30	Coffee break	
10:30 to 11:00	Long talk: Sergio Valcarcel Macua, Aleksi Tukiainen, Daniel Garcia-Ocaña Hernández, David Baldazo, Enrique Munoz de Cote and Santiago Zazo. Diff-DAC: Distributed Actor-Critic for Average Multitask Deep Reinforcement Learning	
11:00 to 11:30	Long talk: Diederik M. Roijers, Denis Steckelmacher and Ann Nowé. <i>Multi-objective Reinforcement Learning for the Expected Utility of the Return</i>	
11:30 to 11:45	Short talk: Jaromir Janisch, Viliam Lisy and Tomas Pevny. Classification with Costly Features using Deep Reinforcement Learning	
11:45 to 12:00	Short talk: Arushi Jain, Khimya Khetarpal and Doina Precup. Safe Option-Critic: Learning Safety in the Option-Critic Architecture	
12:00 to 12:15	Short talk: Thommen Karimpanal George and Roland Bouffanais. Self-Organizing Maps as a Storage and Transfer Mechanism in Reinforcement Learning	
12:15 to 12:30	Short talk: Timothy Verstraeten and Ann Nowé. Reinforcement Learning for Fleet Applications using Coregionalized Gaussian Processes	
12:30 to 12:45	Short talk: Weixun Wang, Jianye Hao, Yixi Wang and Matthew Taylor. Achieving Cooperation Through Deep Multiagent Reinforcement Learning in Sequential Prisoner's Dilemmas	
12:45 to 14:00	Lunch break	
14:00 to 14:30	Long talk: Panayiotis Danassis and Boi Faltings. Courtesy as a Means to Anti-coordinate	
14:30 to 14:45	Short talk: Gabriel De O. Ramos, Bruno Castro Da Silva, Roxana Radulescu and Ana L. C. Bazzan. Learning System-Efficient Equilibria in Route Choice Using Tolls	
14:45 to 15:00	Short talk: Rachna Nanda Kumar, Chad Crawford and Sen Sandip. Effects of Parity, Sympathy and Reciprocity in Increasing Social Welfare	
15:00 to 15:15	Short talk: Jonathan Serrano, Eduardo Morales, Pablo Hernandez Leal, Daan Bloembergen and Michael Kaisers. <i>Learning on a budget using distributional RL</i>	
15:15 to 15:30	Short talk: Daiki Kimura, Subhajit Chaudhury, Ryuki Tachibana and Sakyasingha Dasgupta. Internal Model from Observations for Reward Shaping	
15:30 to 16:00	Coffee break	
16:00 to 18:00	Poster Session A	

Time	Sunday 15 July (Location: Room B4)	
08:30 to 09:30	Keynote: Kagan Tumer. Objective Functions and Autonomy: What the World Cup can teach us about the Future of Al	
09:30 to 10:00	Long talk: Bikramjit Banerjee and Matthew Taylor. Coordination Confidence based Human-Multi-Agent Transfer Learning for Collaborative Teams	
10:00 to 10:30	Coffee break	
10:30 to 11:00	Long talk: Akshat Agarwal, Swaminathan Gurumurthy, Vasu Sharma and Katia Sycara. <i>Mind Your Language: Learning Visually Grounded Dialog in a Multi-Agent Setting</i>	
11:00 to 11:30	Long talk: Mao Li, Tim Brys and Daniel Kudenko. Introspective Reinforcement Learning and Learning from Demonstration	
11:30 to 11:45	Short talk: Mao Li, Yi Wei and Daniel Kudenko. <i>Reinforcement learning from multiple experts demonstrations</i>	
11:45 to 12:00	Short talk: Karl Mason, Jim Duggan and Enda Howley. Maze Navigation using Neural Networks Evolved with Novelty Search and Differential Evolution	
12:00 to 12:15	Short talk: Richard Klima, Daan Bloembergen, Michael Kaisers and Karl Tuyls. Learning robust policies when losing control	
12:15 to 12:30	Short talk: Eric Klinkhammer, Connor Yates, Yathartha Tuladhar and Kagan Tumer. Learning in Complex Domains: Leveraging Multiple Rewards through Alignment	
12:30 to 12:45	Short talk: Jessie Huang, Fa Wu, Doina Precup and Yang Cai. Learning safe policies with expert guidance	
12:45 to 14:00	Lunch break	
14:00 to 14:30	Long talk: Sammie Katt, Frans Oliehoek and Christopher Amato. Efficient Exploitation of Factored Domains in Bayesian Reinforcement Learning for POMDPs	
14:30 to 15:00	Long talk: Biswarup Bhattacharya, Han Ching Ou, Arunesh Sinha, Sze-Chuan Suen, Bistra Dilkina and Milind Tambe. <i>Repeated Active Screening of Networks for Diseases</i>	
15:00 to 15:30	Panel discussion: Participants TBC. Establishing a career in AI	
15:30 to 16:00	Coffee break	
16:00 to 18:00	Awards & closing remarks, followed by Poster Session B	

Poster Session A, Saturday 14 July 16:00 to 18:00	Poster Session B, Sunday 15 July 16:00 to 18:00	
Caroline Player and Nathan Griffiths. Addressing Concept Drift in Reputation Assessment	Aleksandra Malysheva, Aleksei Shpilman and Daniel Kudenko. <i>Learning to Run with Reward</i> <i>Shaping from Video Data</i>	
Di Wu, Guillaume Rabusseau, Vincent François-Lavet, Doina Precup and Benoit Boulet. Optimizing Home Energy Management and Electric Vehicle Charging with Reinforcement Learning	John Burden and Daniel Kudenko. Using Uniform State Abstractions For Reward Shaping With Reinforcement Learning	
Mathieu Reymond, Christophe Patyn, Roxana Radulescu, Geert Deconinck and Ann Nowe. Reinforcement Learning for Demand Response of Domestic Household Appliances	Gabriel de La Cruz, Yunshu Du and Matthew Taylor. <i>Pre-training Neural Networks with Human</i> <i>Demonstrations for Deep Reinforcement Learning</i>	
Xinlei Pan, Eshed Ohn-Bar, Nicholas Rhinehart, Yan Xu, Yilin Shen and Kris M. Kitani. Human-Interactive Subgoal Supervision for Efficient Inverse Reinforcement Learning	Francis Lawlor, Rem Collier and Vivek Nallur. Towards a Programmable Framework for Agent Game Playing	
Tambet Matiisen, Aqeel Labash, Daniel Majoral, Jaan Aru and Raul Vicente. Do deep reinforcement learning agents model intentions?	Su Zhang and Matthew Taylor. Enhanced Learning from Multiple Demonstrations with a Two-level Structured Approach	
Dustin Dannenhauer, Michael Floyd, Matthew Molineaux and David Aha. Learning from Exploration: Towards an Explainable Goal Reasoning Agent	Golden Rockefeller, Scott Chow, Yathartha Tuladhar and Kagan Tumer. Policy Progress Score for Automatic Task Selection in Curriculum Learning	
Oliver Roesler and Ann Nowé. Simultaneous Action Learning and Grounding through Reinforcement and Cross-Situational Learning	David Isele and Kikuo Fujimura. <i>The Sidewalk Problem</i>	